Principal Researche		Yoshihiko NAKAM	URA		Number of		5	
					Researchers			
Research Institution		Professor, Departmen	t of Mechano-I	nformatics,	Location of		Bunkyo-ku,	
· Department · Title		Graduate School of Information Science and		Institution		Tokyo		
	,	Technology, Universit	y of Tokyo					
Title of	Deployment of Dynamical Information Processing Model of Intelligence							
Project								
Abstract of	The essence of human intelligence and mind is considered lying in the behavior of							
Research	nonlinear dynamics that emerged from the structured and multi layered hierarchy of the body							
Project	sensory-motor system and the nervous system. This research sets its own goal at building a							
	hypothetical model that reaches machine intelligence on the basis of dynamical information							
	processing. The machine intelligence here implies the principal mechanism that obtains the							
	cognitive skills of symbol manipulation, linguistic extrospection and introspection, and							
	communications through multi layered hierarchical developments of sensory and motor map.							
	We take proof-by-synthesis approaches to establish the principal mechanism. The verification is to be done by experiments using humanoid robots and simulation using musculoskeletal human body models. The uniqueness of this research is in the fact that we design the information processing system based on continuous behavior of dynamics and applying it to the machines with as much complexity as a humanoid robot. This research project is not only challenging from informatics point of view, but also of academic							
	significance exploring the missing link between neural and cognitive sciences.							
References	ces (1) Yoshihiko Nakamura, Woojin Chung and Ole Jacob. Sordalen, "Design and Control or							
	the Nonholonomic Manipulator," IEEE Trans. on Robotics and Automation, Vol.17, No.1,							
	pp.48-59, February, 2001.							
(2) Y. Nakamura and K. Yamane, "Dynamics Computation of Structure-Varyin							Kinematic	
	Chains and Its Application to Human Figures," IEEE Trans. on Robotics and Autom							
	Vol.16, No.2, pp.124-134, 2000.							
Term of Project	Fiscal years 2003-2007 . (5years)							
Budget	FY200)3 FY2004	FY2005	FY200	6 FY200	7	TOTAL	
Allocation	14	4,700 27,900	23,300	14	.,000	,000,	93,900	
(in thousand of yen)								
Homepage Addı	ress		http://www.yr	ttp://www.ynl.t.u-tokyo.ac.jp				